

Segmentation of random textures by morphological and linear operators

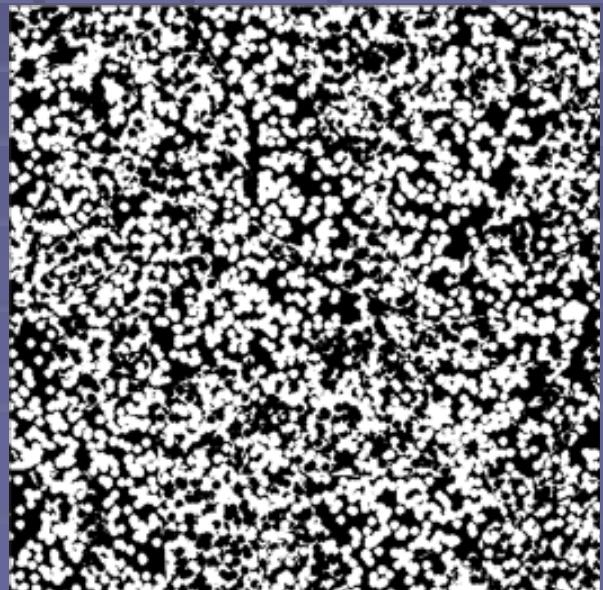
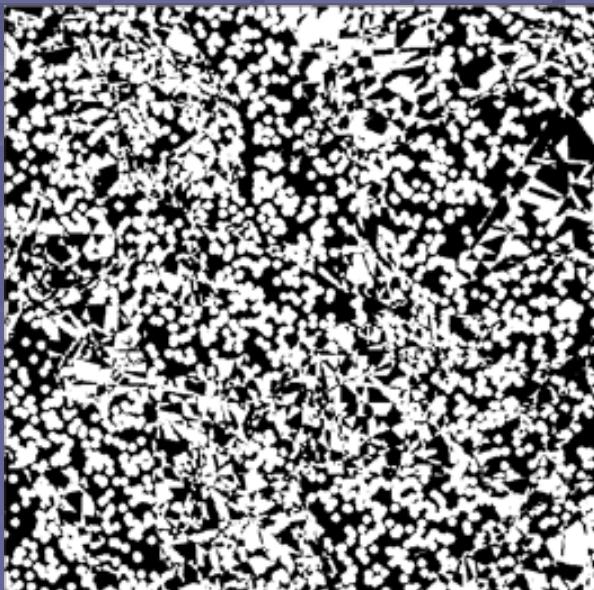
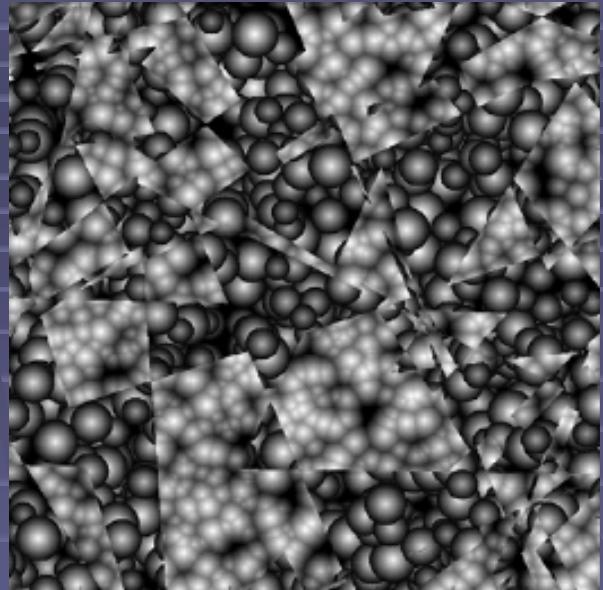
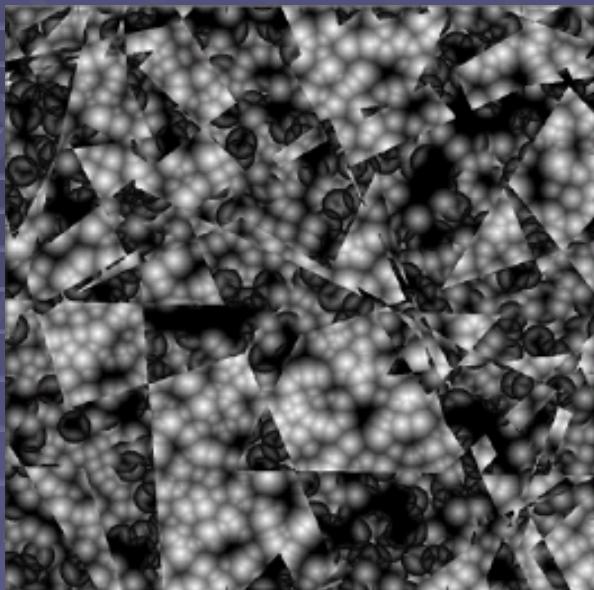
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October 11th, 2007



Objectives

Segmentation
of digital
and binary
random
textures



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Outline

1. Pixel texture description
2. Machine learning
3. Application
 1. Simulated random texture images
 2. Experiments



Theoretical approach of random textures

- Textures -> fluctuations at a small scale, uniformity at a large scale.
- It requires the use of a probabilistic approach
- A random texture is completely known from its Choquet capacity.
- Good candidates for texture descriptors can be provided by estimates of probabilities obtained after dilations (or erosions) by compact sets.

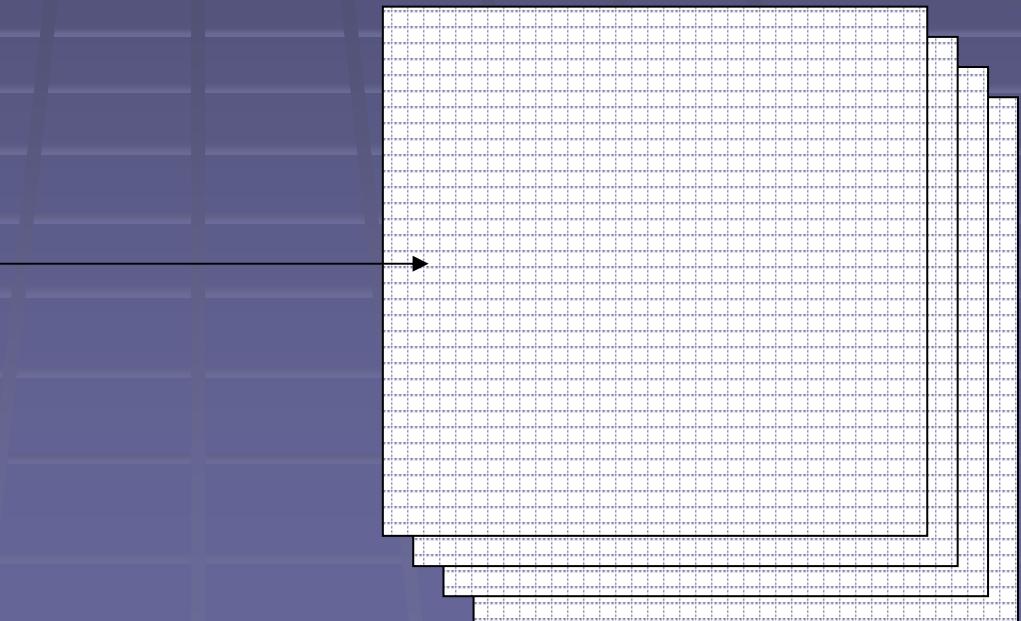
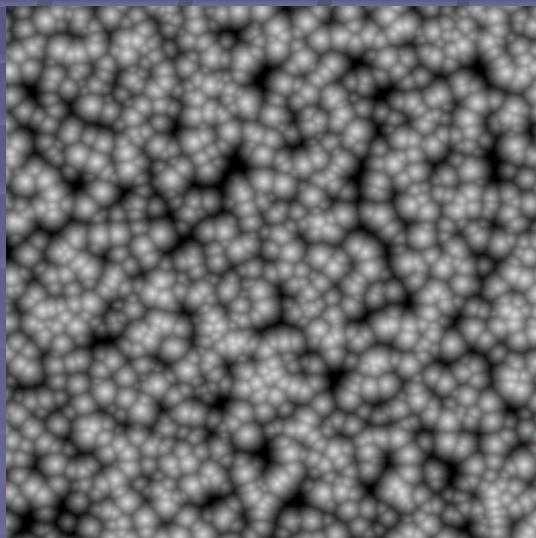


Texture segmentation

- **From Image to pixels**
- **Classification of pixels into textures:** needs for a **local characterization** of textures
 - Transform the image by dilations, erosions (« pixel » approach), and **generate a multispectral image** from the collection of compact sets K
 - Use of the local estimates of $T(K)$, $T(g)$ inside a neighborhood $B(x)$, to **generate a multispectral image**
 - Use of measures μ_i with a compact support K_i and estimate $\mu_i(A)$, to **generate a multispectral image**; examples: linear filters, multiscale convolution, local measurement of Minkowski functionals of a RS,...

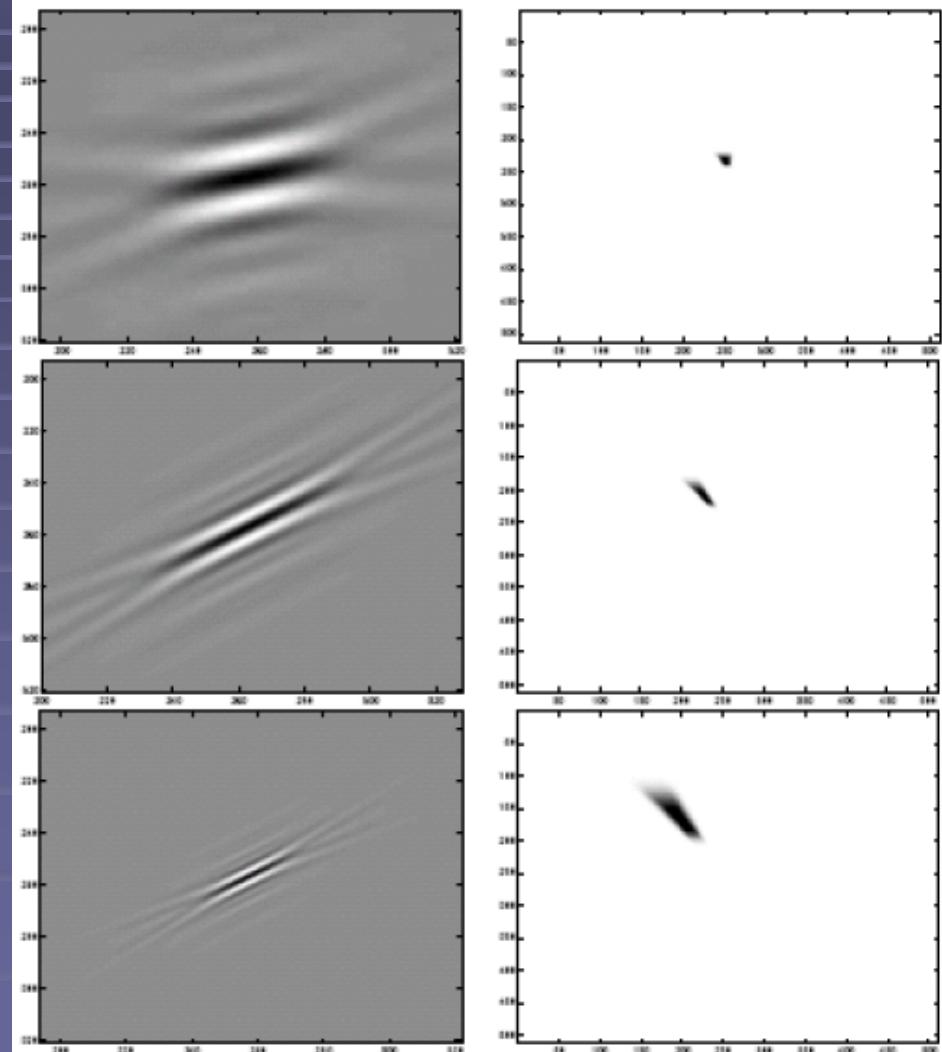
Texture properties description

- Texture properties calculated for each pixel, accounting for local properties in neighborhoods with varying scales.

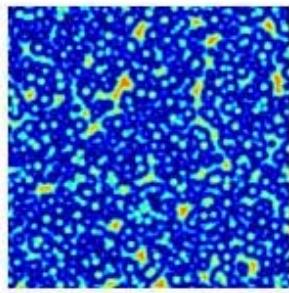


Linear Filters : Curvelets (1)

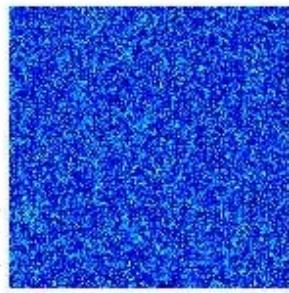
- Directional and frequential filtering
- 4 frequencies
- 16 angles
- Descriptor dimension = 26



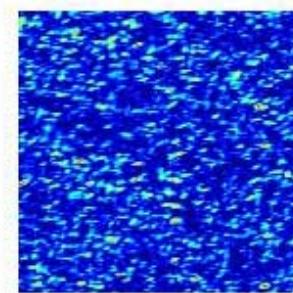
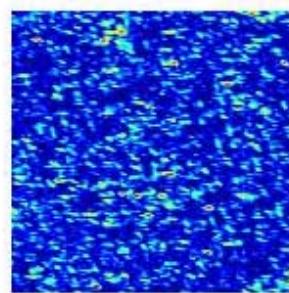
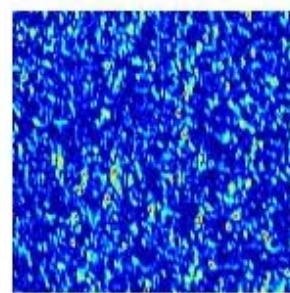
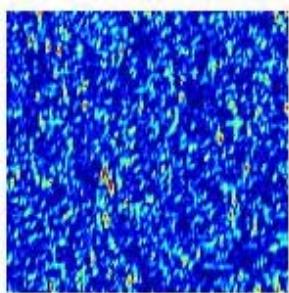
Curvelets (2)



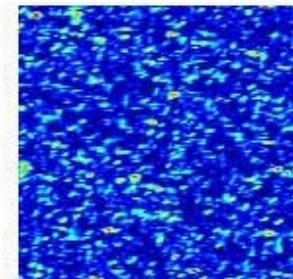
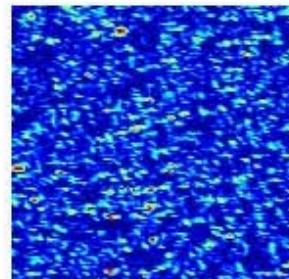
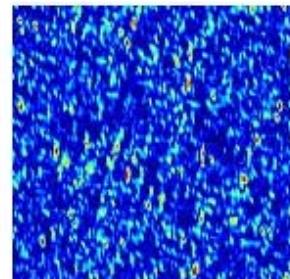
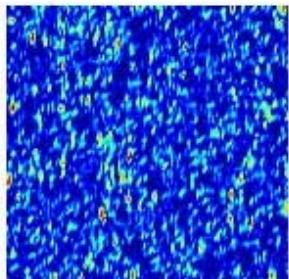
Lowest Frequency



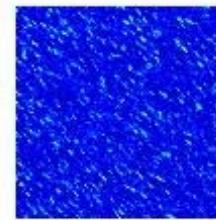
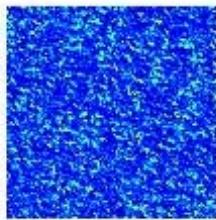
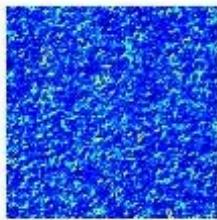
Highest Frequency



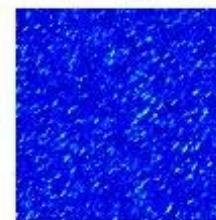
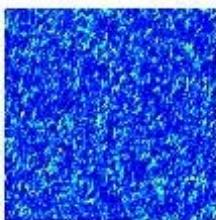
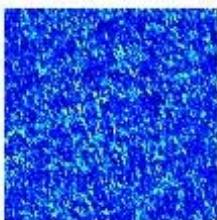
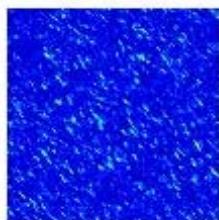
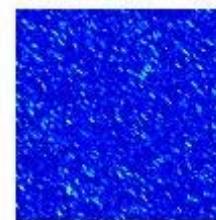
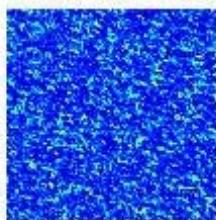
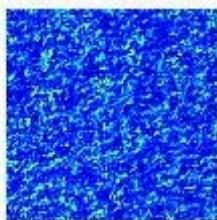
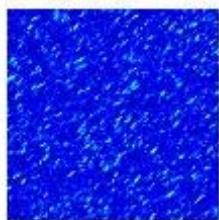
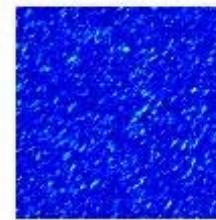
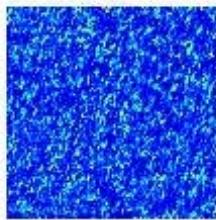
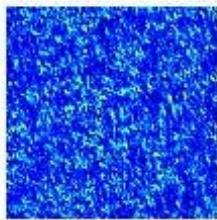
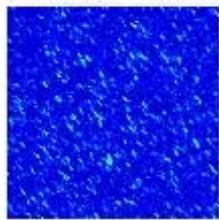
Low Frequency, 8 angles



Curvelets (3)

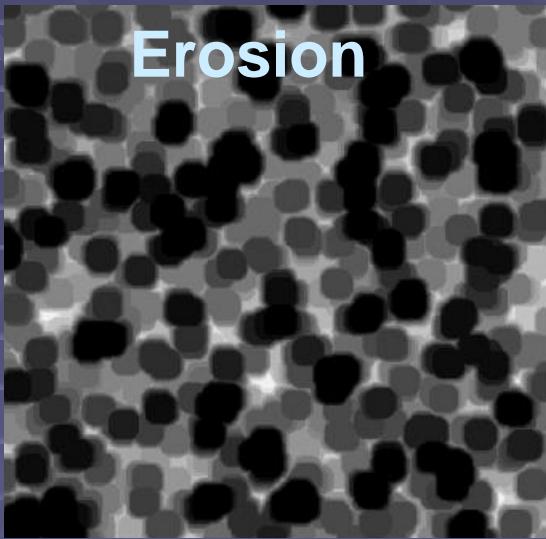


High Frequency, 16 angles

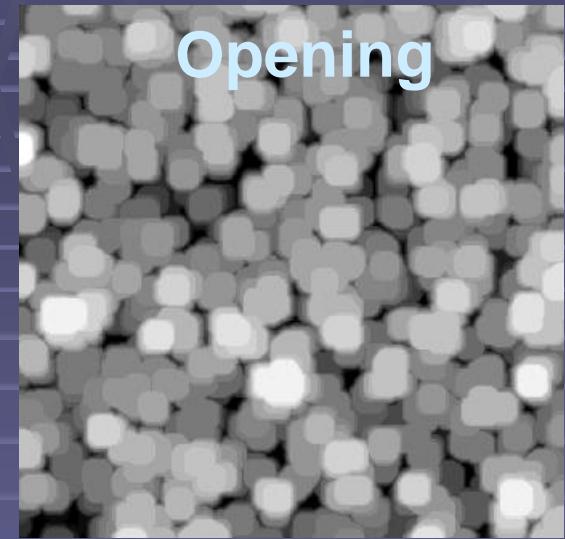


Morphological description (1)

Erosion



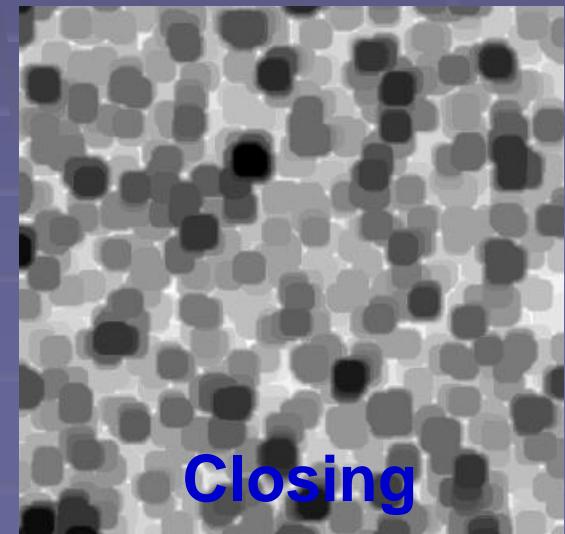
Opening



Dilatation



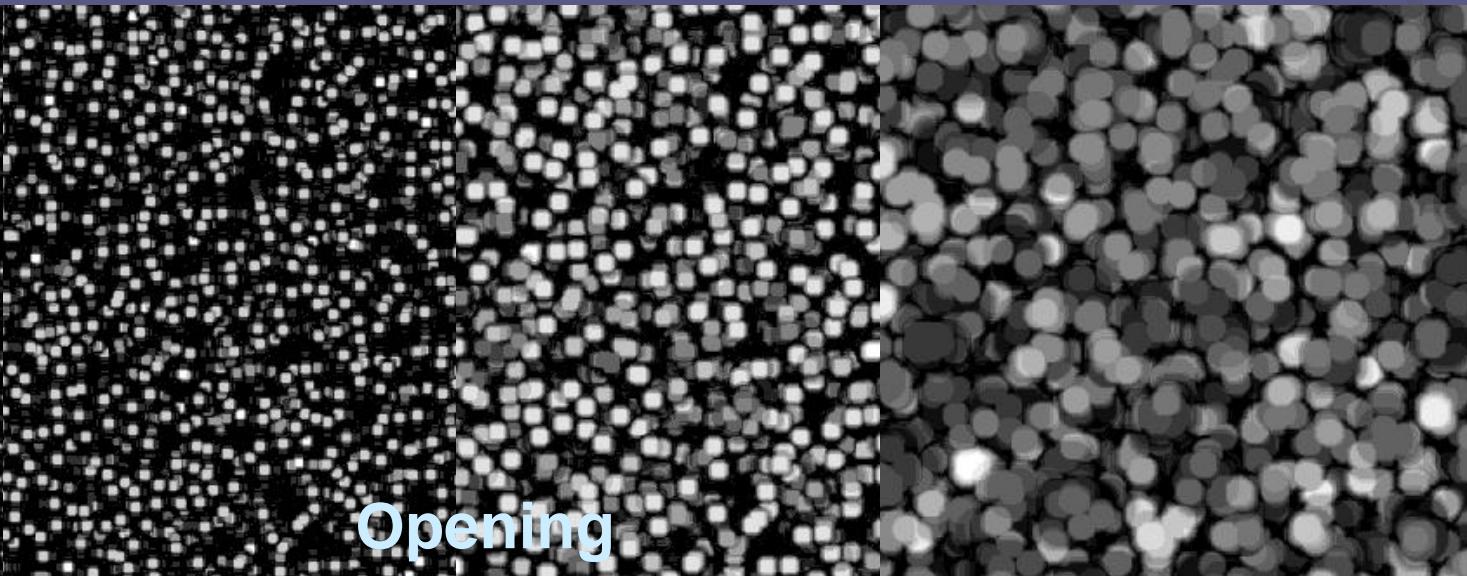
Closing



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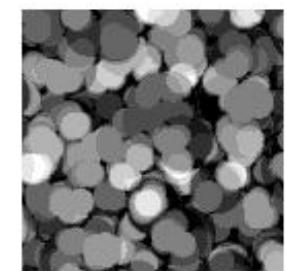
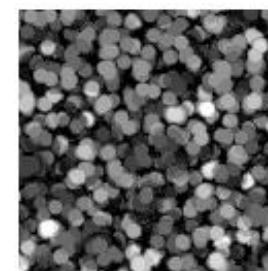
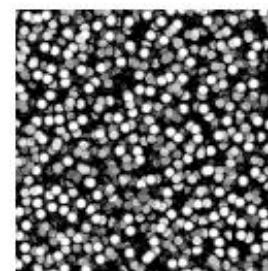
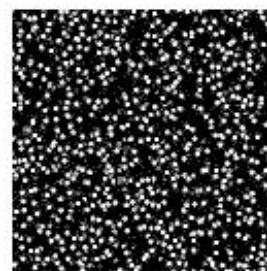
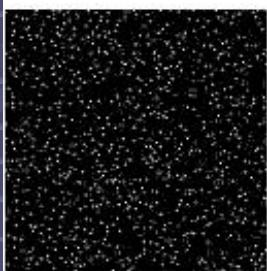
Morphological Descriptors (2)

- Succession of openings and closings by structuring elements (disk, segment) of increasing sizes.
- Differences between the two successive operations

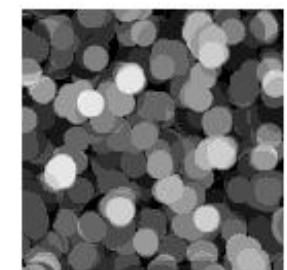
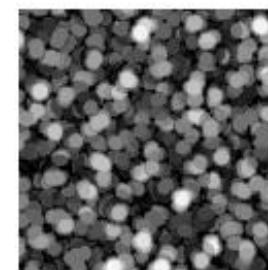
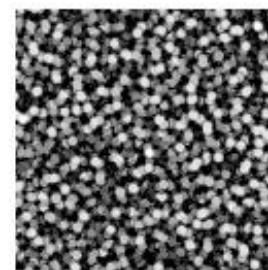
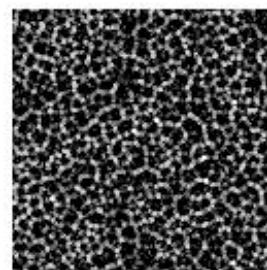
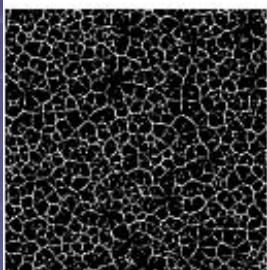


Morphological Descriptors (2)

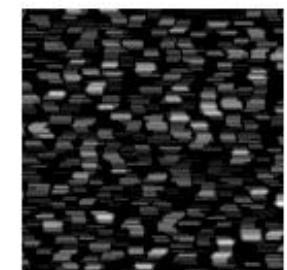
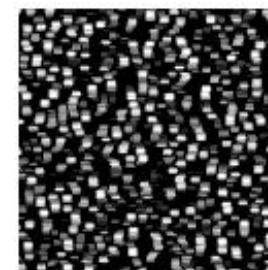
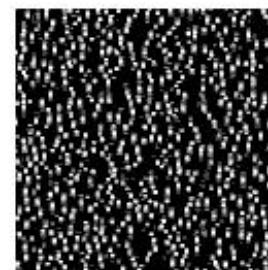
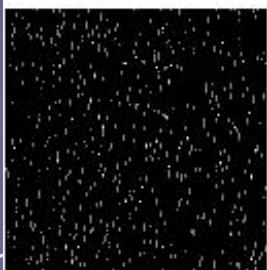
Open
Disk



Close
Disk

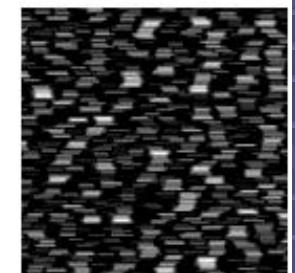
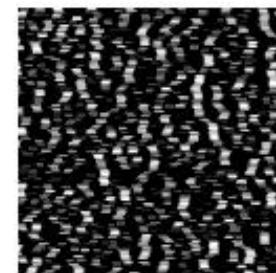
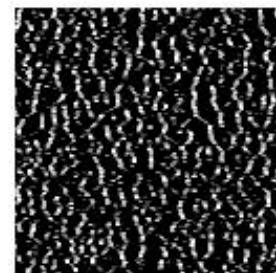


Open
H line

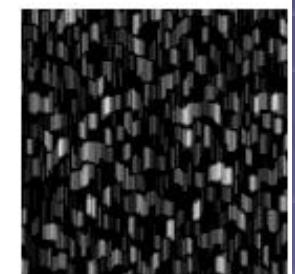
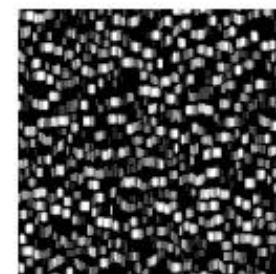
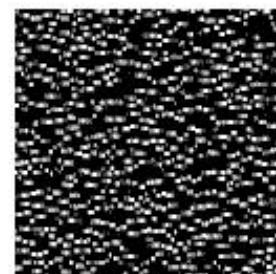
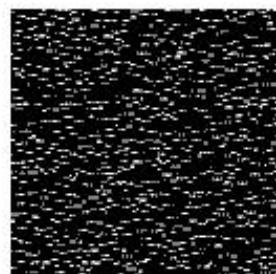


Morphological Descriptors(3)

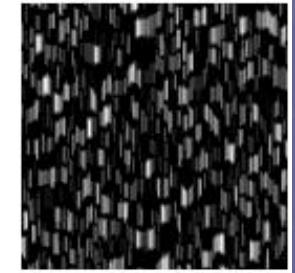
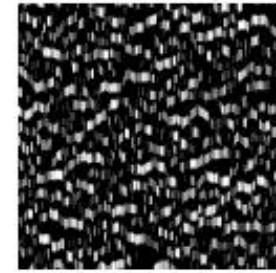
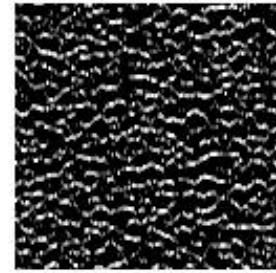
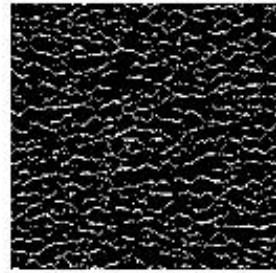
Close
H line



Open
V line



Close
V line



Texture descriptors

The texture descriptors is a combination of:

- 26 curvelets, combining 4 frequencies and 16 directions
- 126 morphological operations, with disks, vertical and horizontal lines as structuring elements and the series of sizes :
 - Opening/Closing, $[2, 4, 8, 16, 32] \times 2 + 1$ pixels.
 - Opening/Closing, $[1, 2, 3, 4, 5, 7, 9, 12] \times 2 + 1$ pixels.
 - Erosion/Dilatation, $[1, 2, 3, 4, 5, 7, 9, 12] \times 2 + 1$ pixels.

Each descriptor is averaged in a window sizing between 1x1 and 60x60.

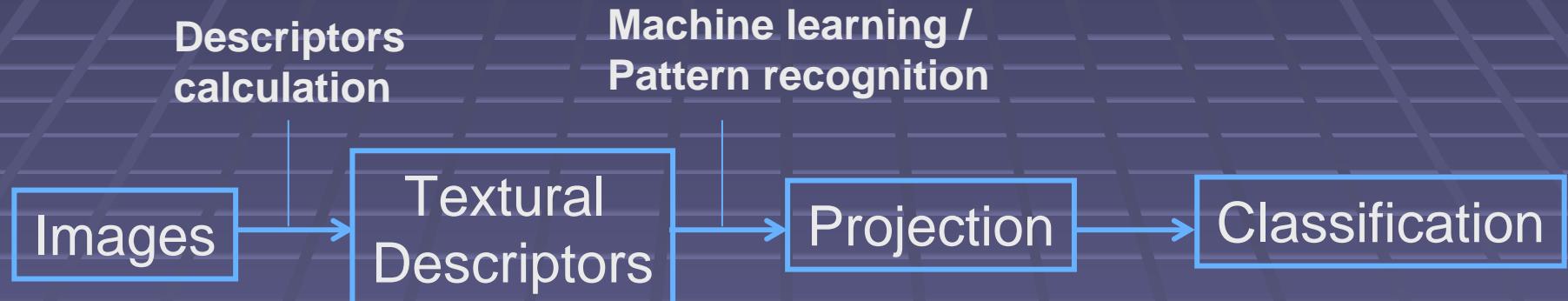


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Methodology



Find the best descriptor projection to separate classes



Linear Discriminant Analysis (LDA)

- Discriminant Analysis: to classify objects into one of two or more groups based on a set of features describing the objects (e.g. Texture properties.)
- Supervised learning method: it needs that each object owns an identified label.
- Produces new variables, as a linear combinations of the initial descriptors that are effective to separate classes
- Use of independent training and testing pixels to evaluate errors with a good accuracy.

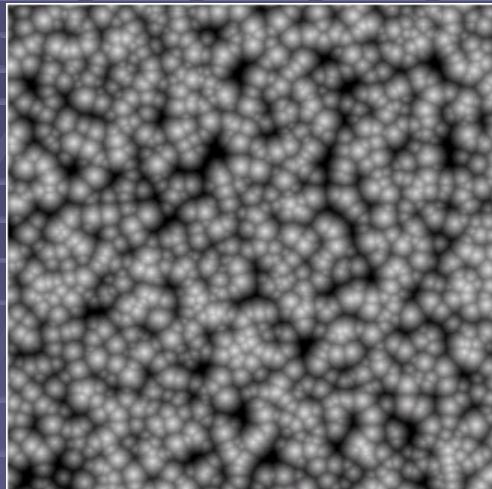


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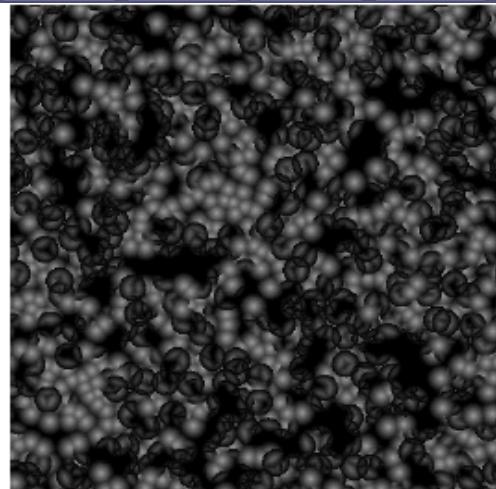


Simulated random textures



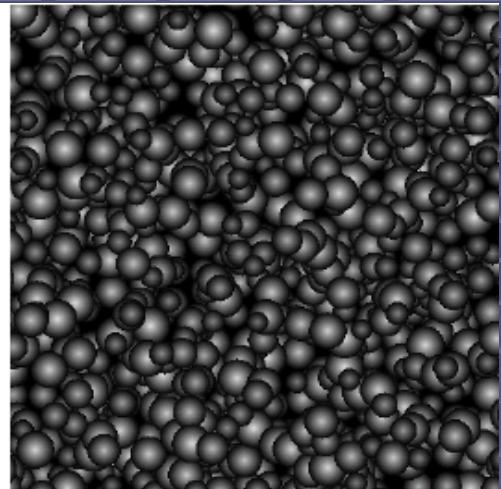
Boolean RF

Boolean RS



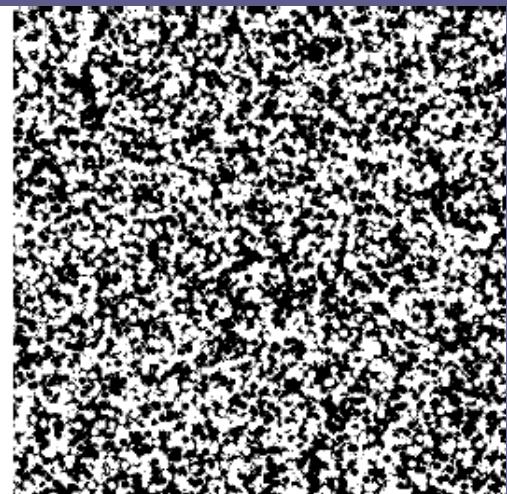
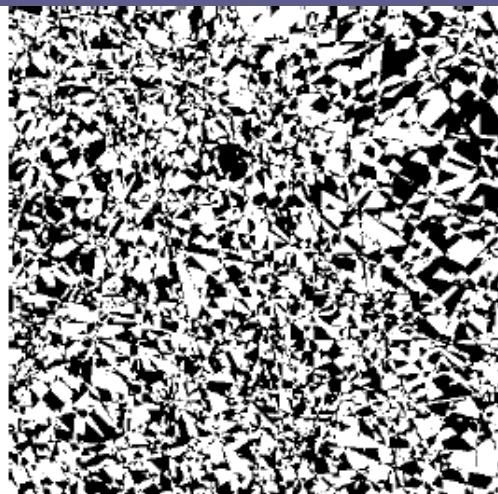
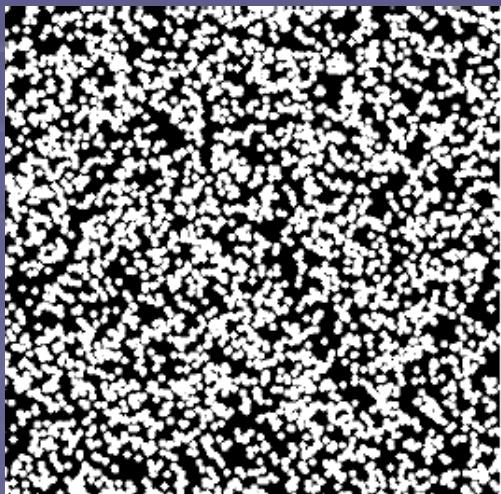
Sequential Alternate RF

Poisson mosaic RS

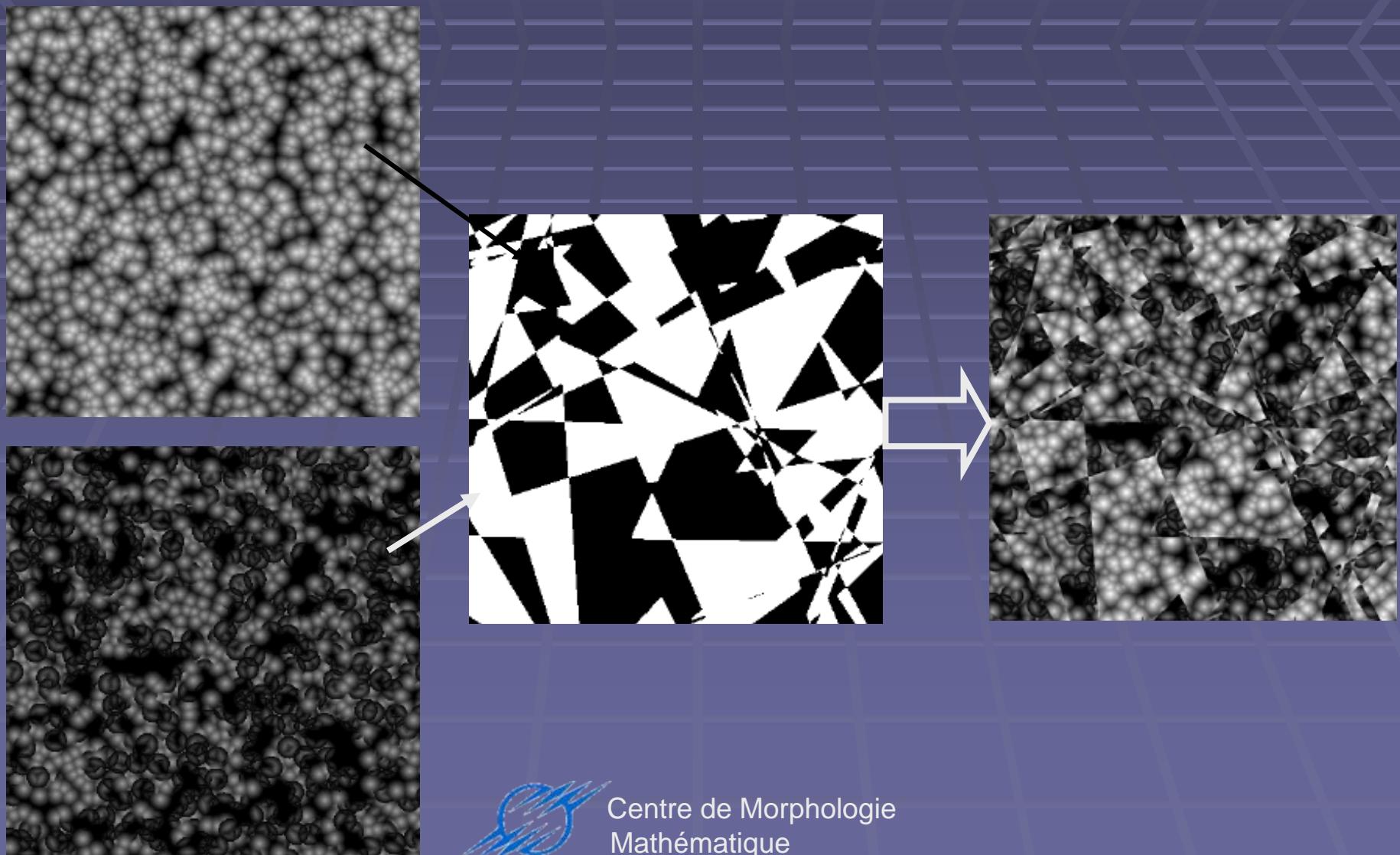


Dead leaves RF

Binary dead leaves RS

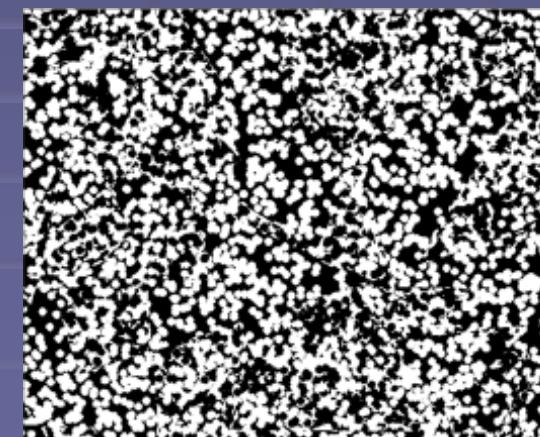
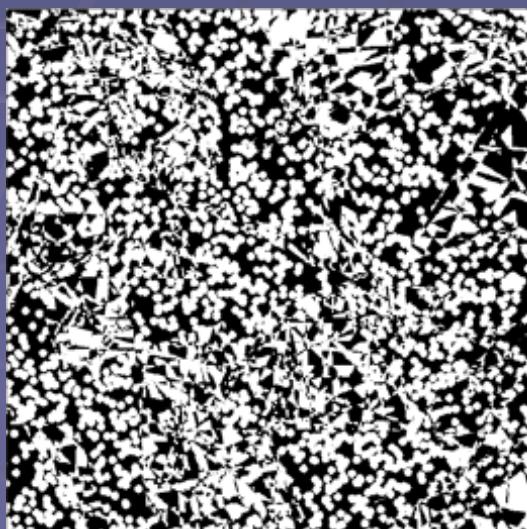
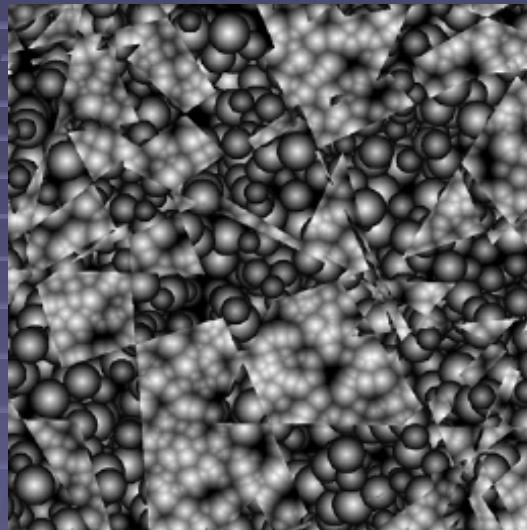
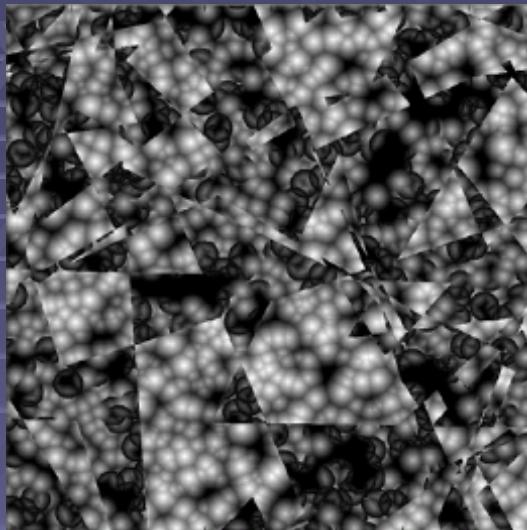


Patchwork images (1)



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Patchwork images (2)



4 images.

Very small areas
with different
textures
compared to the
size of the primary
grain.

Avalaible on the
internet

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Learning Procedures

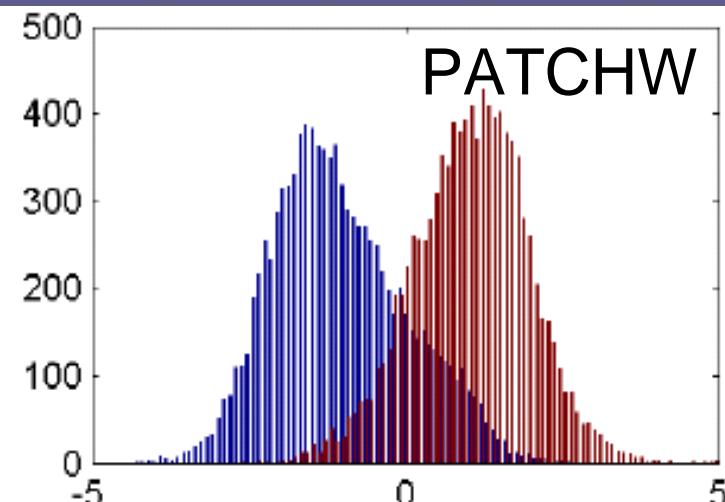
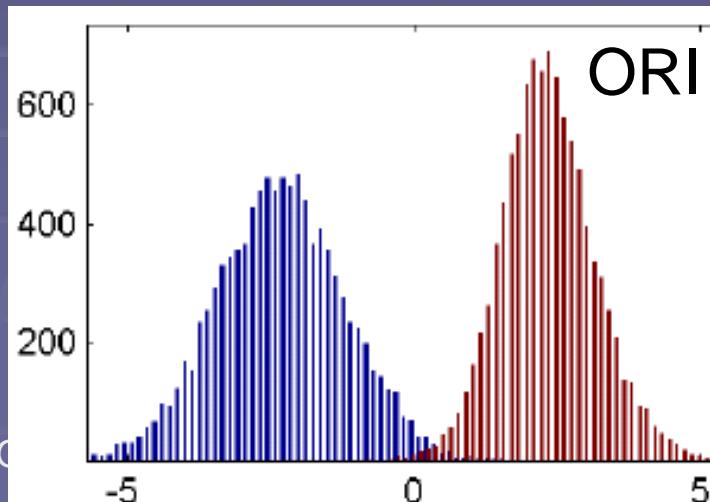
1. Learning from original images « ORI »

Best separation of the two textures

2. Learning from patchwork images

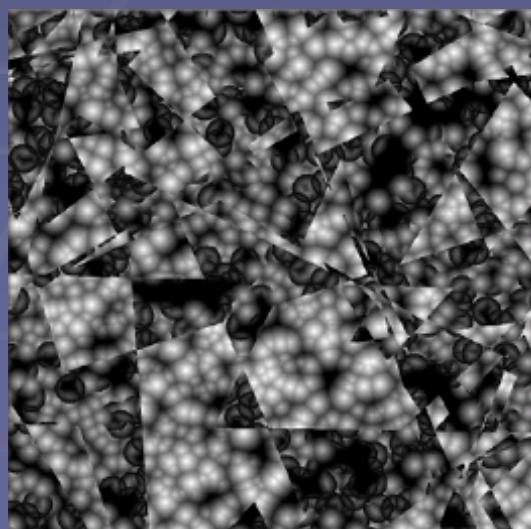
« PATCHW »

Best separation even on border areas



Misclassification error

- All pixels of patchwork image are projected on the first LDA axis and classified.
- Using the knowledge of the mask, the misclassification error is evaluated.

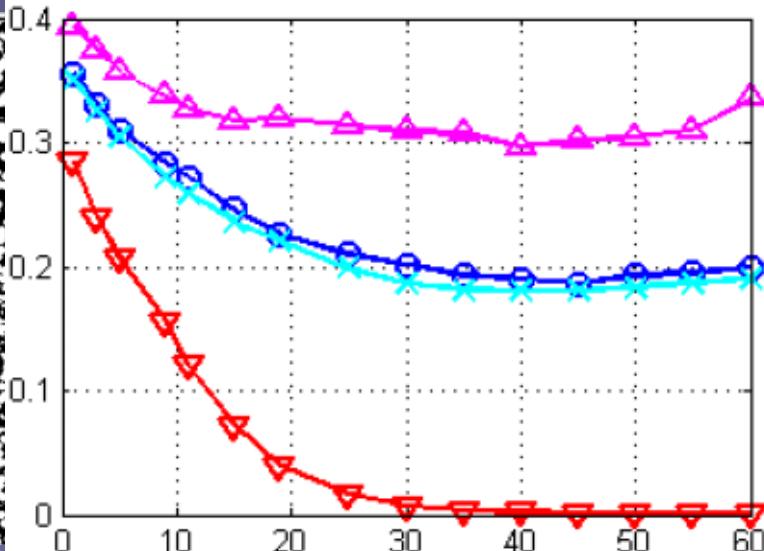
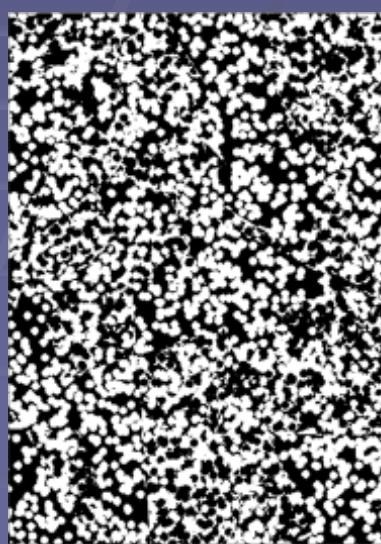
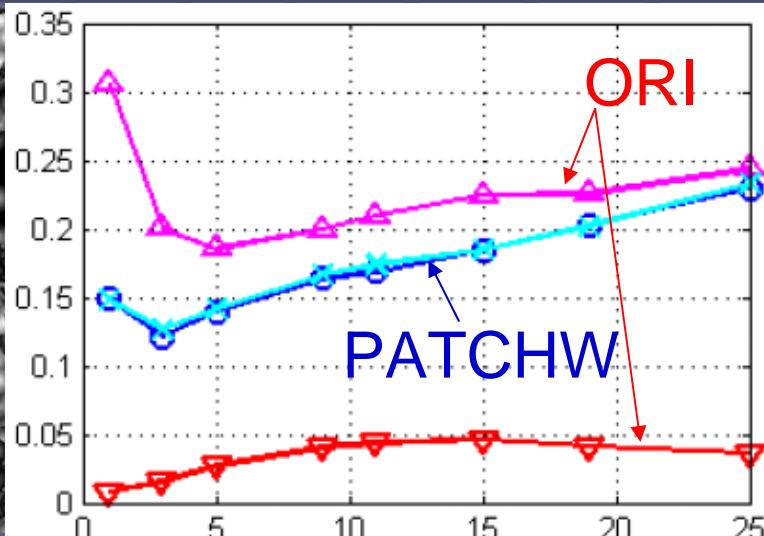
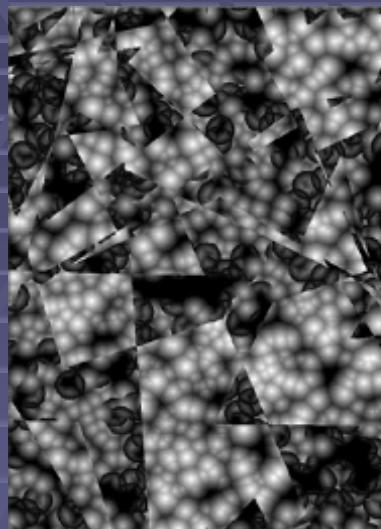


	ORI	PATCHW
Learning test error	1.0	15.5
Misclassification error	29.5	15.7



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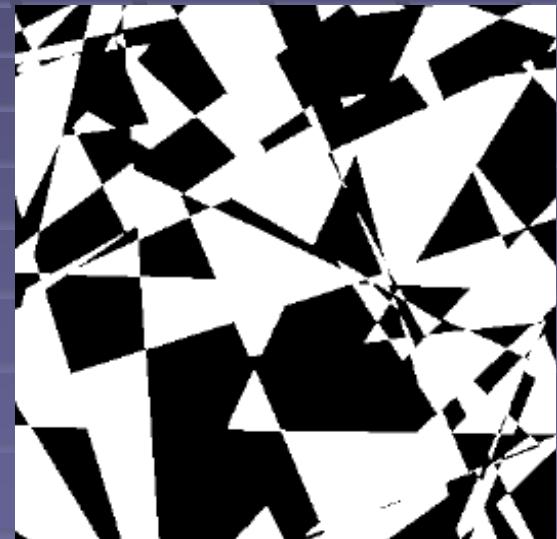
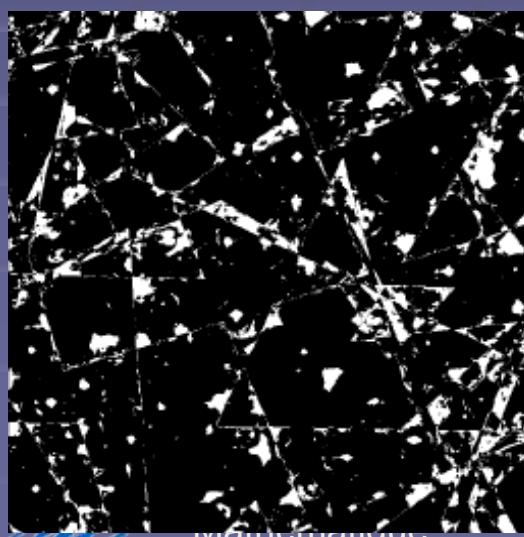
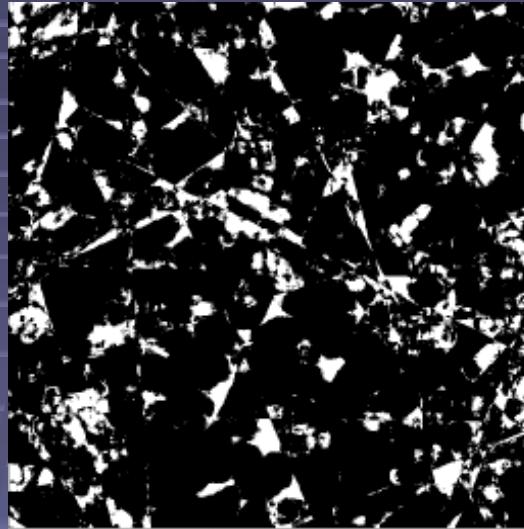
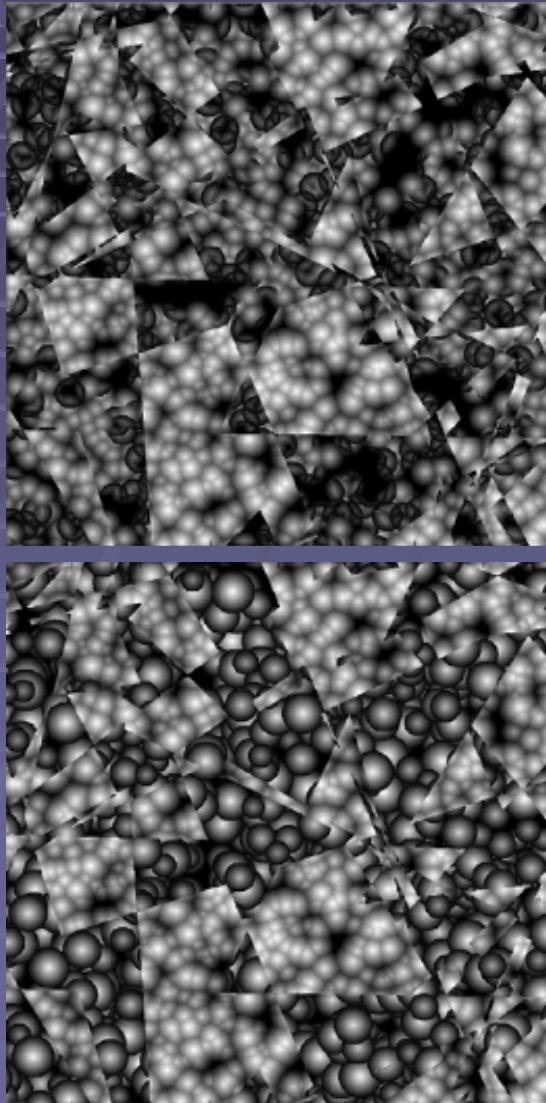
Averaging window sizes



Only a small box
3x3 slightly
improves the results
Descriptor sizes
well adapted

It need a 35x35
averaging window.
Textural motif are
larger for binary
images

Localization of misclassified pixels



ie

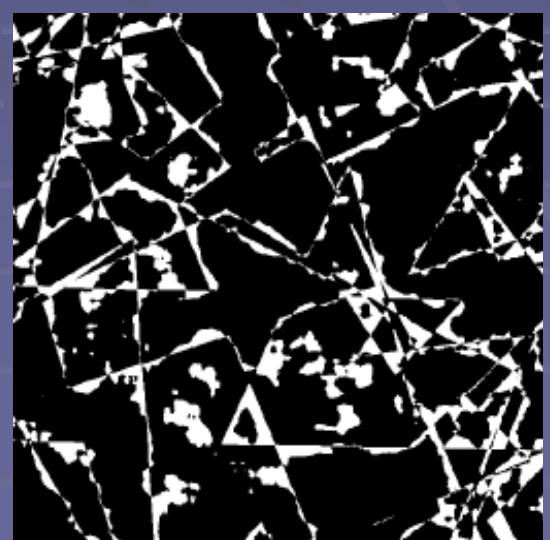
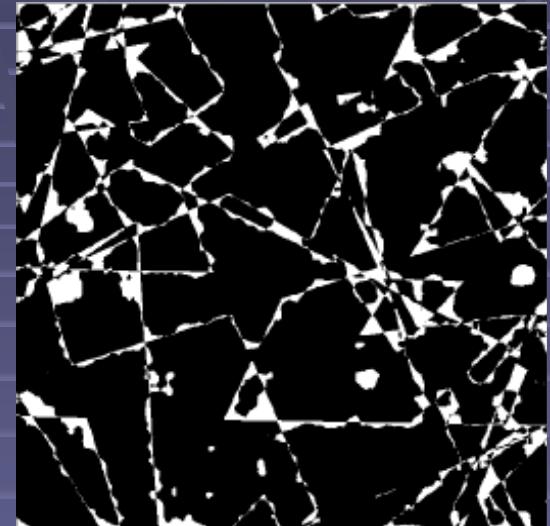
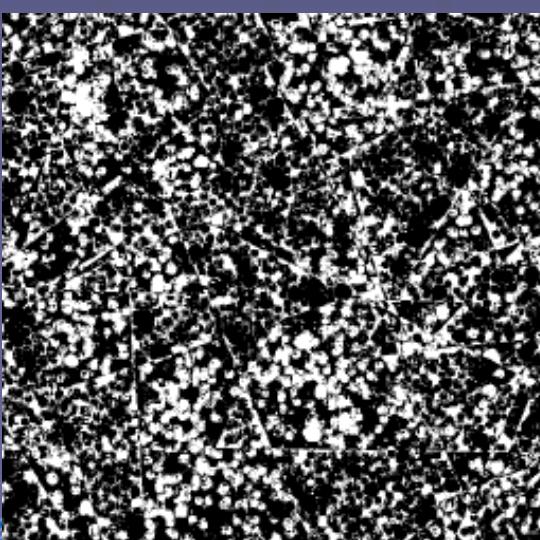
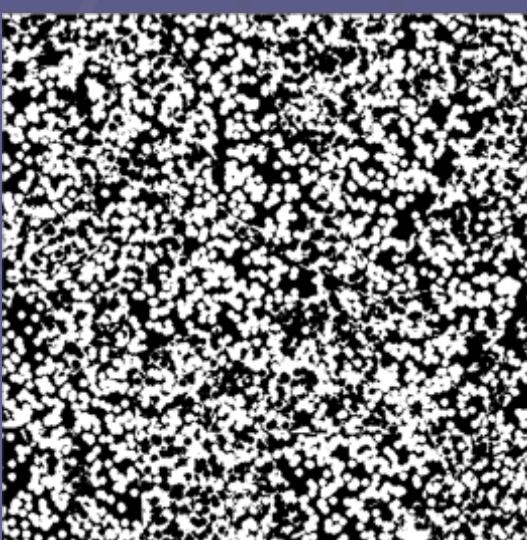
mathematique

Localization of misclassified pixels

Without averaging

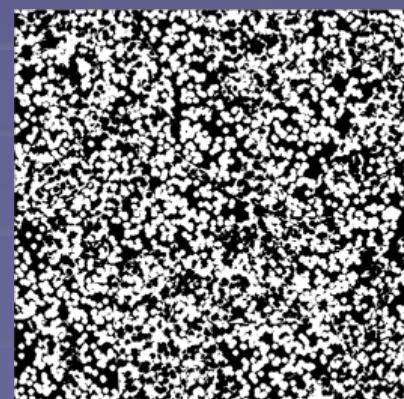
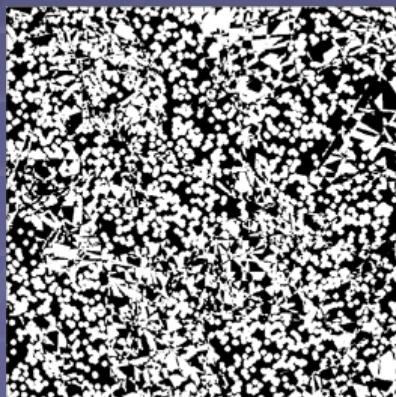
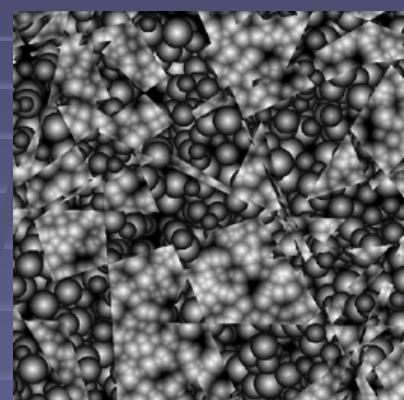
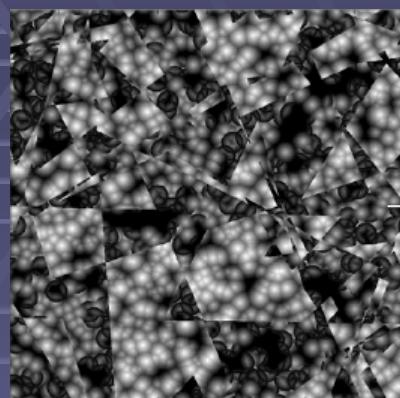


With 35x35 averaging



Final classification errors

LDA vs SVM



LDA

→ 15.7 %

SVM

→ 9.7 %

→ 9.4 %

→ 12.1 %

→ 13.5 %

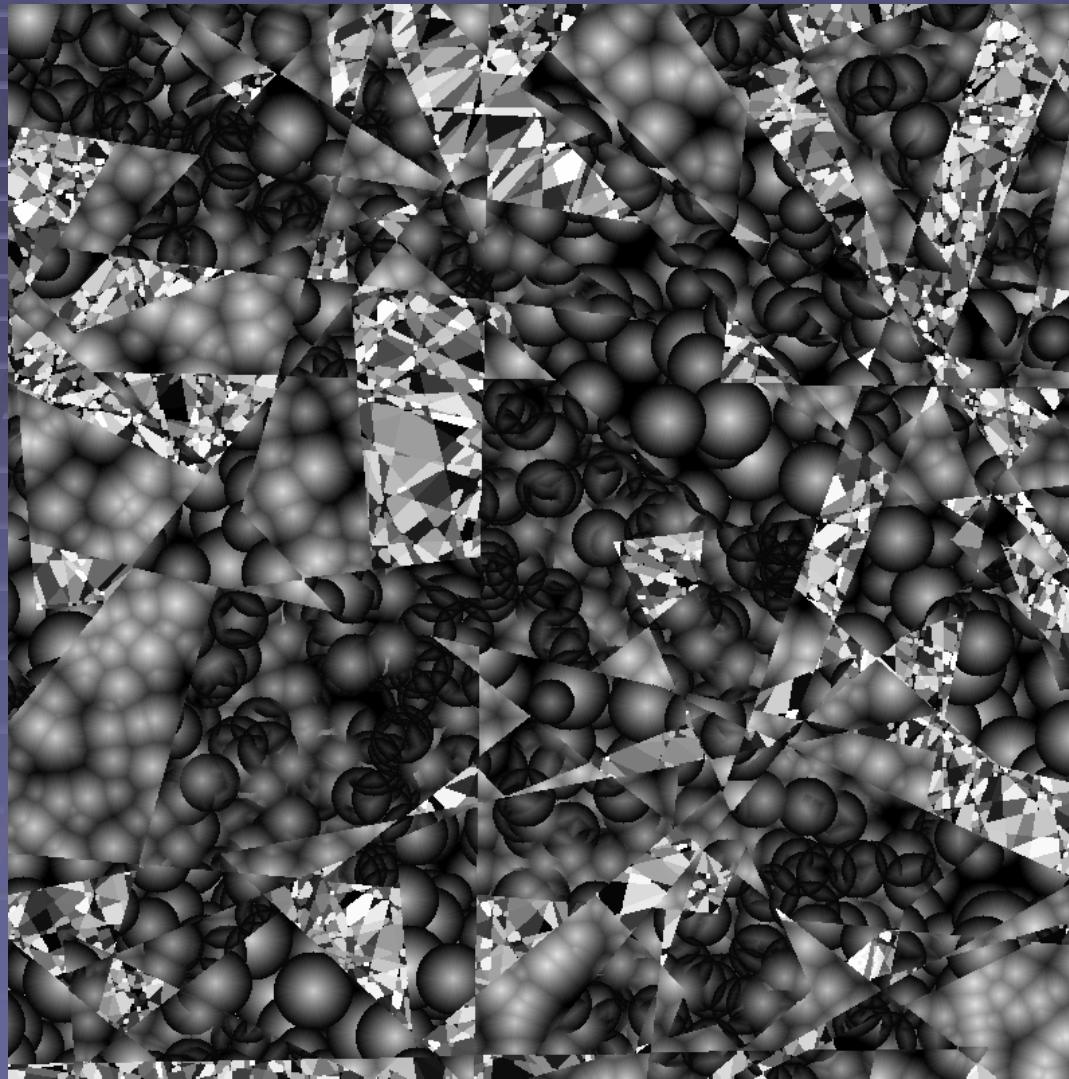
→ 18.1 %

Efficiency of descriptors

- Larger contribution to the LDA projection: disk structuring element (isotropic textures)
- Erosions-Dilations most relevant for binary images
- Opening/closing most relevant for grey level images
- Curvelets more relevant for binary images
- Large scale structuring elements irrelevant here



Extension to more textures (4)

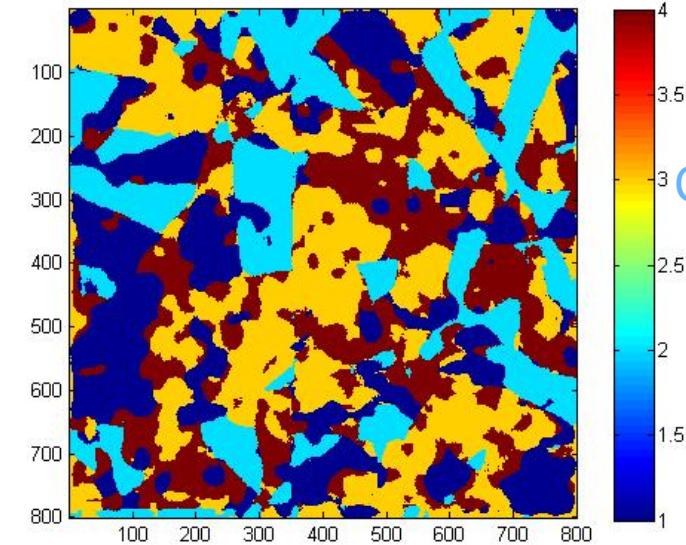
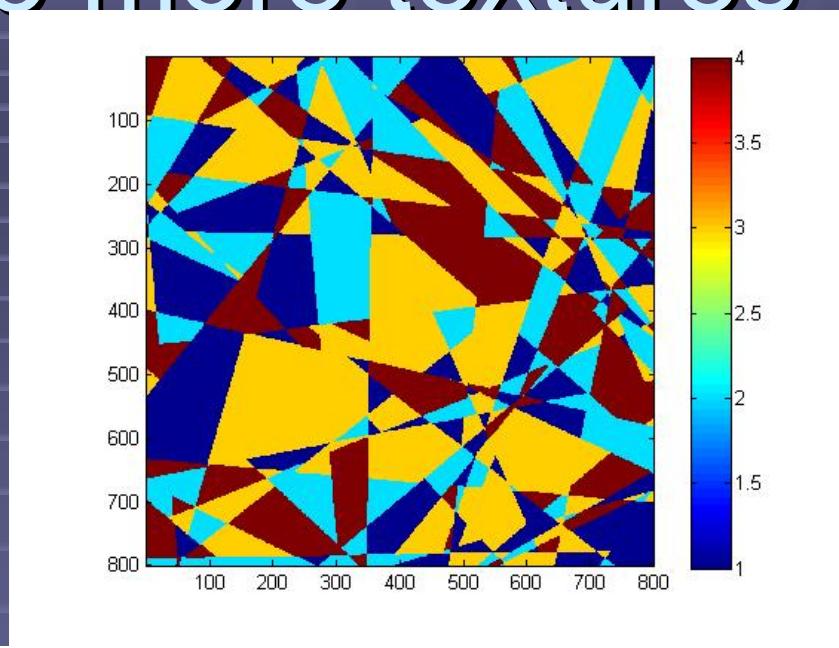
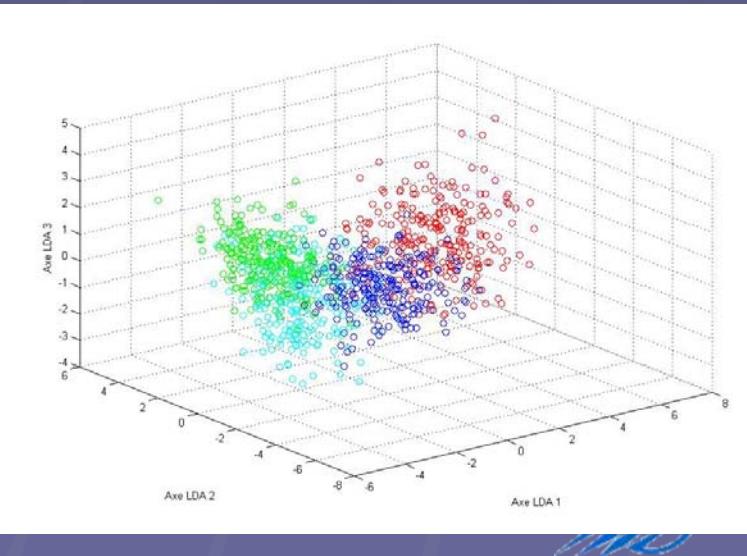
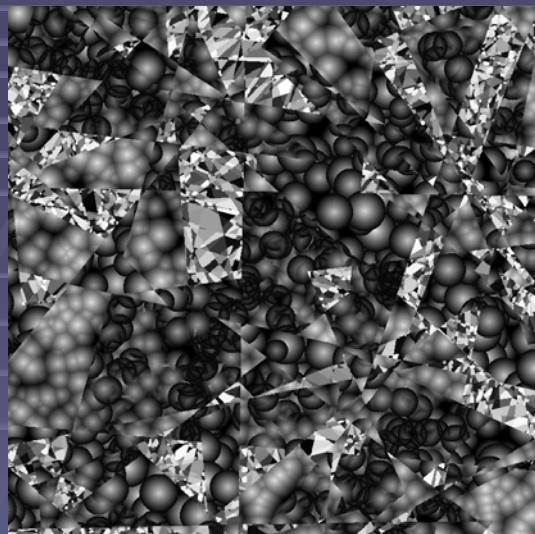


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Extension to more textures



mask

Classification
Error
Rate:
28%

Conclusion

- Basic morphological image transformations and curvelets provide efficient texture descriptors at the pixel scale
- This description combined with statistical learning method is efficient for the segmentation according to the local texture.
- The training procedure has to be made on a selection of pixels from the patchwork image in order to minimize the boundary effect.
- Successful application of the methodology to texture extraction on steel plates

